

Online Continual Learning for Embedded Devices

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Code Available

<https://github.com/tyler-hayes/Embedded-CL>

Overview

- ❖ Continual learning is needed for making **real-time updates and inferences** on embedded devices
- ❖ Embedded continual learning can enable **new applications**: home robots, user personalization on mobile devices, augmented/virtual reality headsets, and more
- ❖ **Challenge**: Embedded devices have **limited memory** and **compute capacity** due to hardware constraints
- ❖ **Goal**: Perform a comprehensive study of how well online continual learners perform with mobile CNNs

Embedded Continual Learning Criteria



Online learning and inference in a compute and memory constrained environment



The ability to learn from data in any order without catastrophic forgetting



Making no assumptions about the availability of task labels during inference



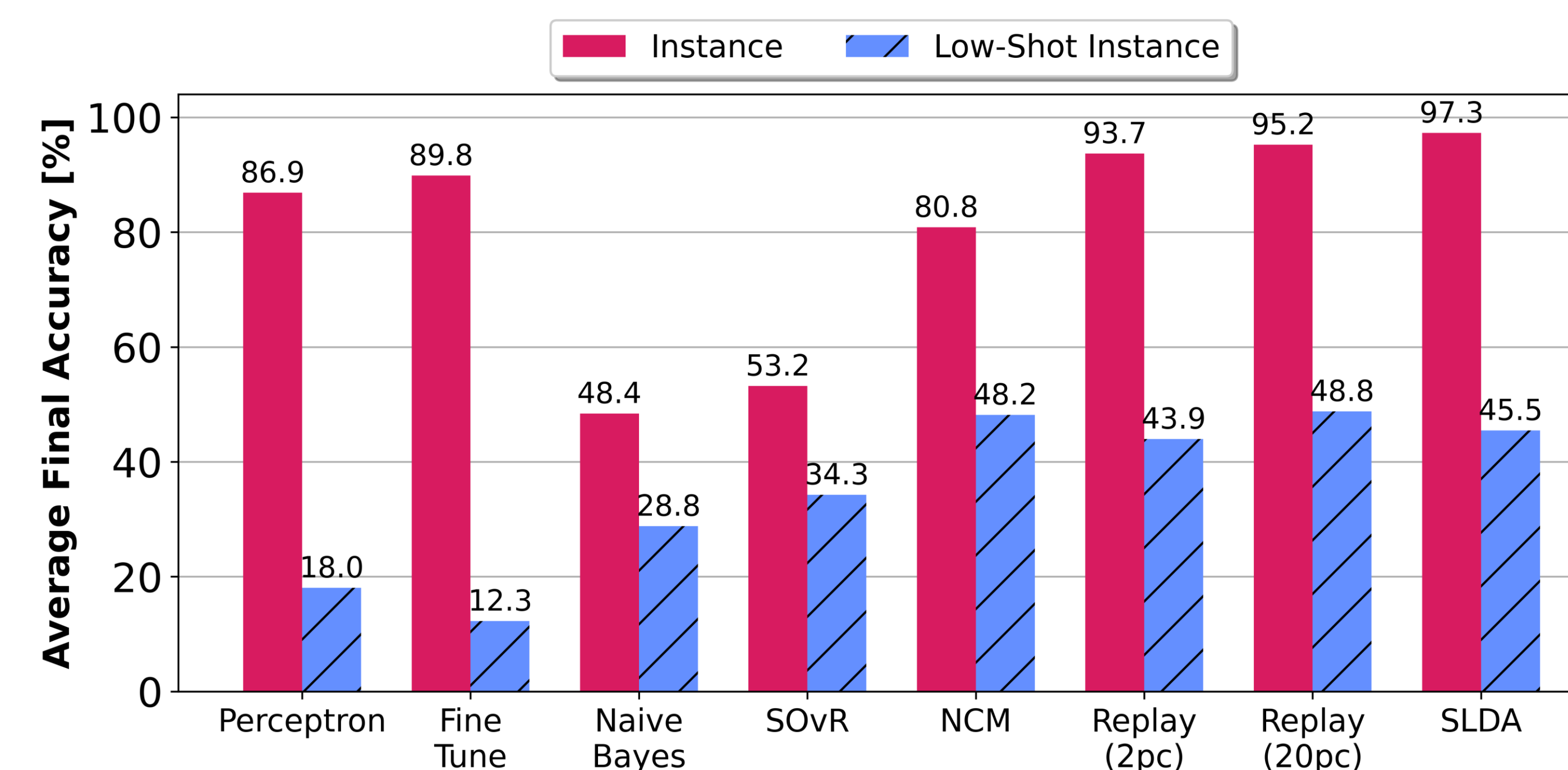
Efficiently learning and generalizing with as few labeled examples as possible

Experimental Setup

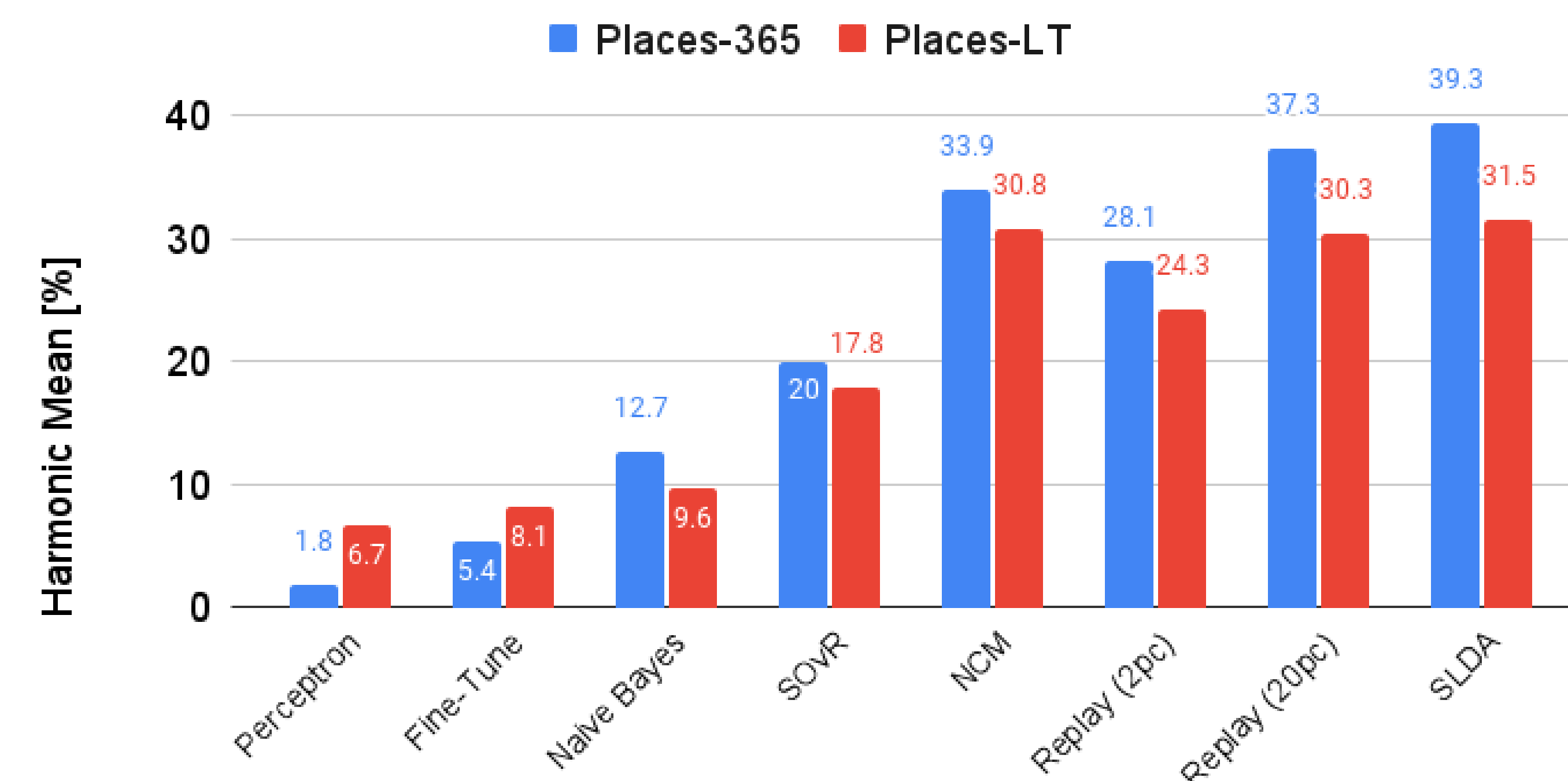
- ❖ **Pre-train** mobile CNN backbone with supervised learning on **ImageNet-1k**
- ❖ Incrementally update the **output layer** of the CNN
- ❖ **Mobile CNNs**: MobileNet-v3 (Small & Large), EfficientNet (B0 & B1), ResNet-18
- ❖ **Online Learners**: Perceptron, Fine-Tune, Naïve Bayes, Stream One-v-Rest (SOvR), Nearest Class Mean (NCM), Replay, Stream Linear Discriminant Analysis (SLDA)
- ❖ **Datasets**: OpenLORIS (Videos), Places-365, Places-Long-Tail (Places-LT)

Results

OpenLORIS Results



Places Results



Overall Results

Factors Evaluated:

Ω: classification efficacy, compute, memory

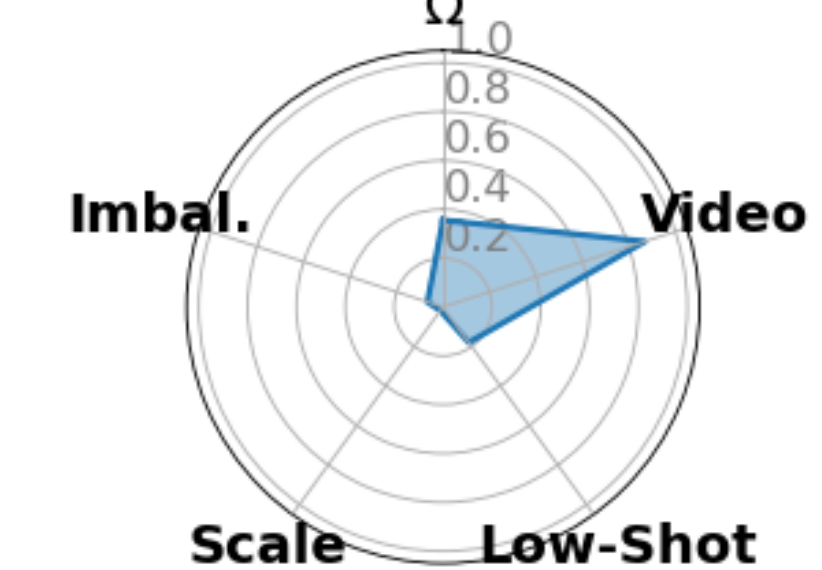
Video: ability to learn from temporally correlated videos

Low-Shot: ability to generalize from few inputs

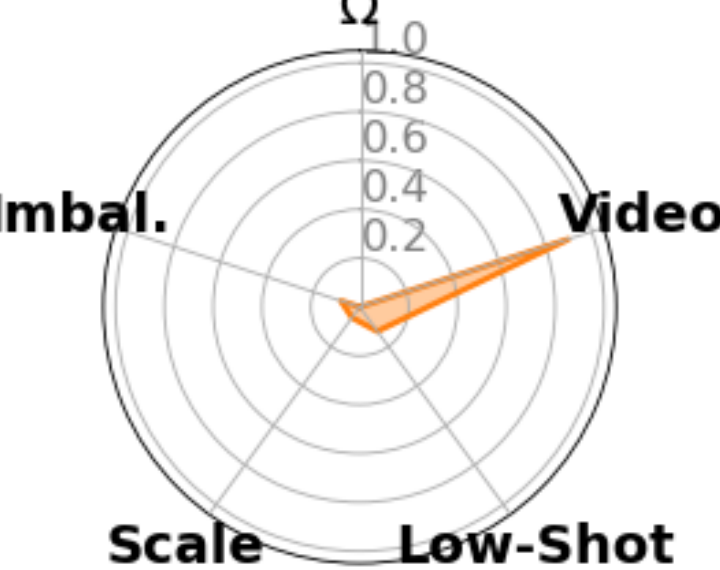
Scale: ability to scale to large-scale data

Imbal: ability to perform well on imbalanced data

Perceptron (0.30)



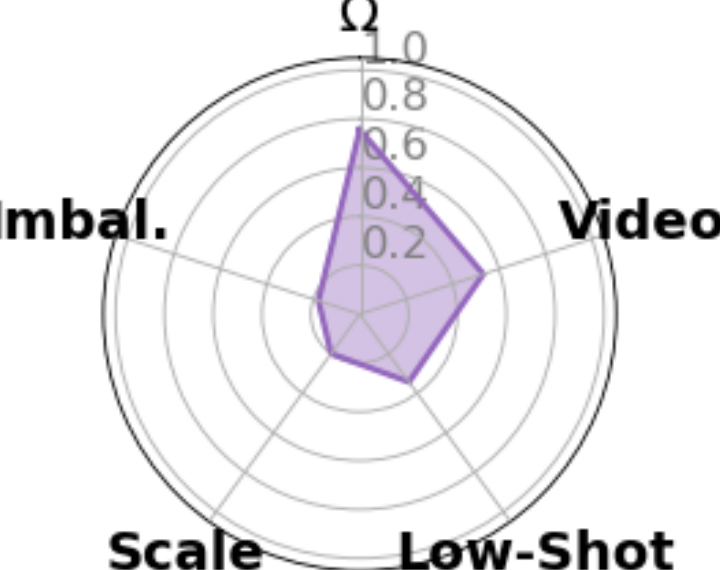
Fine-Tune (0.23)



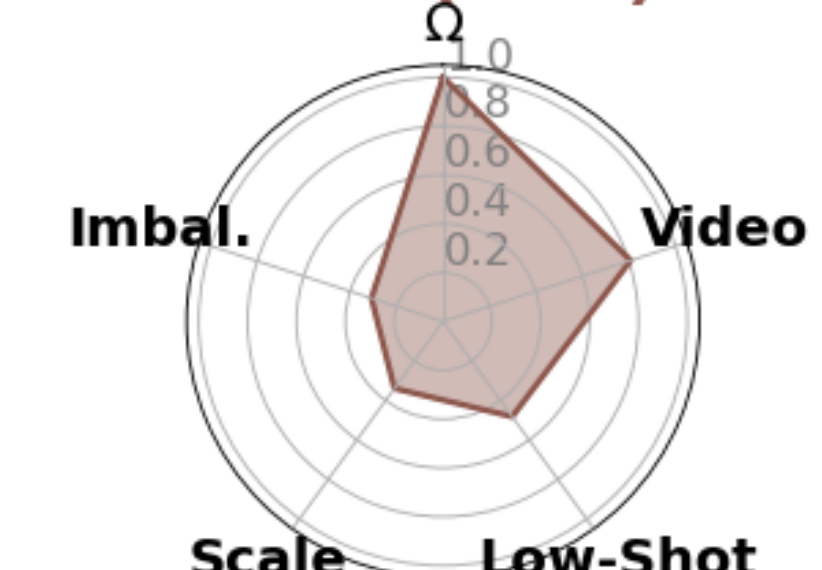
Naive Bayes (0.29)



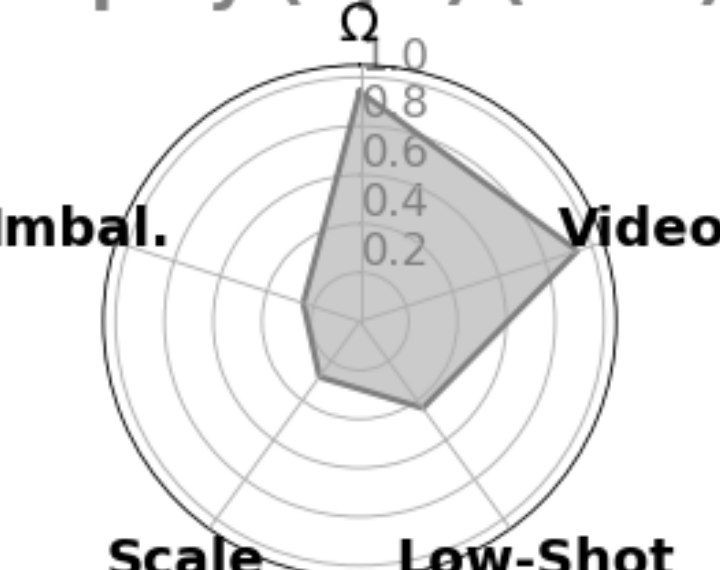
SOvR (0.40)



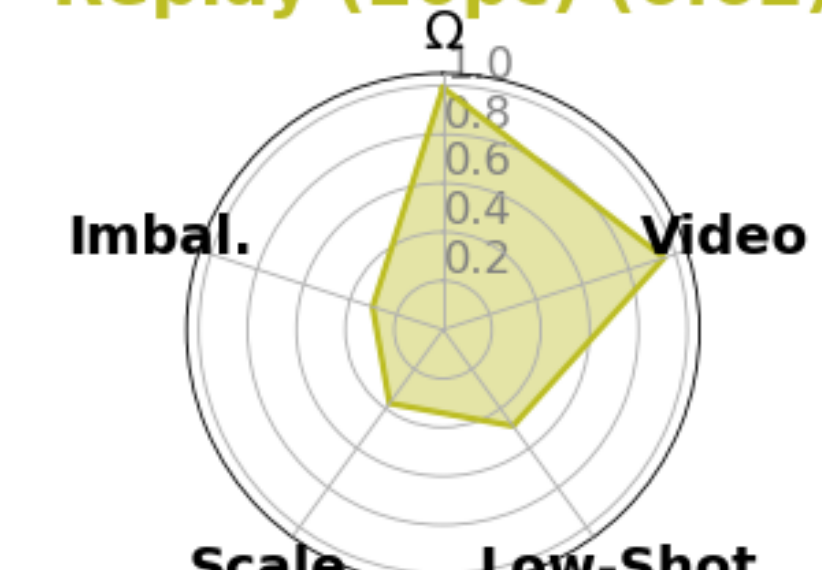
NCM (0.59)



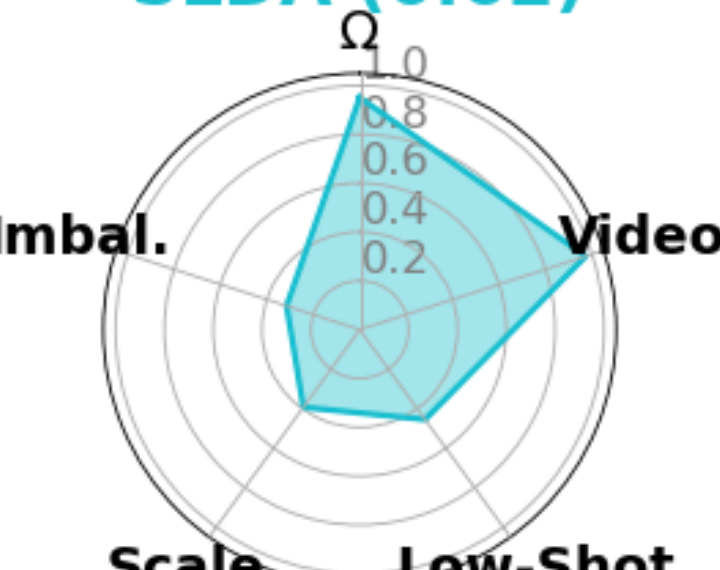
Replay (2pc) (0.57)



Replay (20pc) (0.62)



SLDA (0.62)



Summary

- ❖ We established **online continual learning baselines** for embedded applications subject to: imbalanced data streams, large-scale data streams, video streams, and low-shot video streams
- ❖ **Replay (20pc)** and **SLDA** performed the best across experiments
- ❖ **NCM** also performed well and used less memory and compute
- ❖ **EfficientNet CNNs** yielded the best performance across methods

Acknowledgements:

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